

14.2 Limits and Continuity:

We now extend the concepts of limits and continuity to the case that f is a real valued function defined on a set D in \mathbb{R}^2 (or \mathbb{R}^3).

Definition: We say that the *limit* of $f(x, y)$ as (x, y) approaches (x_0, y_0) is L if $|f(x, y) - L|$ can be made arbitrarily small by choosing $0 < |(x, y) - (x_0, y_0)|$ small (but not 0). We write

$$\lim_{(x,y) \rightarrow (x_0,y_0)} f(x, y) = L.$$

The subtlety here, that did not arise in functions of a single variable, is that $f(x, y)$ must get close to L no matter how (x, y) goes to (x_0, y_0) . For example it is quite possible that $\lim_{x \rightarrow x_0} f(x, y_0)$ exists but $\lim_{(x,y) \rightarrow (x_0,y_0)} f(x, y)$ does not.

Examples:

$$\lim_{(x,y) \rightarrow (1,3)} \sin x + \frac{y}{x-2} = \sin 1 - 3$$

$$\lim_{(x,y) \rightarrow (2,2)} \frac{x^2 - y^2}{y - x} = \lim_{(x,y) \rightarrow (2,2)} -(x + y) = -4$$

$$\lim_{(x,y) \rightarrow (2,0)} \frac{x \sin y}{y}$$

Counterexample:

$$\lim_{(x,y) \rightarrow (0,0)} \frac{xy}{x^2 + y^2} \text{ does not exist}$$

The reason is that if we approach the origin along the straight line $y = mx$ (where m is the slope) then $xy/(x^2 + y^2) = mx^2/(x^2 + m^2x^2) = m/(1 + m^2)$ and so the limiting value depends on the path of approach and that means there is no limit as $(x, y) \rightarrow (0, 0)$.

Curvature: The curvature is a measure of how fast a curve turns. It is the reciprocal of the radius of the “osculating” circle. The curvature of the curve \vec{r} at $\vec{r}(t)$ is

$$\kappa(t) = \frac{|\vec{v}(t) \times \vec{a}(t)|}{|\vec{v}|^3}$$

Example: Consider $\vec{r} = \cos 2\pi t \vec{i} + \sin 2\pi t \vec{j} + t \vec{k}$. Then

$$\begin{aligned}
 \vec{v}(t) &= -2\pi \sin 2\pi t \vec{i} + 2\pi \cos 2\pi t \vec{j} + \vec{j} \\
 \vec{T}(t) &= \frac{\vec{v}(t)}{\sqrt{4\pi^2 + 1}} \\
 \vec{a}(t) &= -4\pi^2 \cos 2\pi t \vec{i} - 4\pi^2 \sin 2\pi t \vec{j} \\
 \vec{N}(t) &= -\cos 2\pi t \vec{i} - \sin 2\pi t \vec{j} \\
 \vec{B}(t) &= \frac{1}{\sqrt{4\pi^2 + 1}} \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ -2\pi \sin 2\pi t & 2\pi \cos 2\pi t & 1 \\ -\cos 2\pi t & -\sin 2\pi t & 0 \end{bmatrix} \\
 &= \frac{1}{\sqrt{4\pi^2 + 1}} [\sin 2\pi t \vec{i} - \cos 2\pi t \vec{j} + 2\pi \vec{k}] \\
 \kappa &= \frac{|\vec{v} \times \vec{a}|}{|\vec{v}(t)|^3} \\
 &= \frac{4\pi^2 \sqrt{4\pi^2 + 1}}{(\sqrt{4\pi^2 + 1})^3} = \frac{4\pi^2}{4\pi^2 + 1}
 \end{aligned}$$